

Bris

A high-resolution data-driven machine learning model for weather forecasting

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Basics of initial-state machine learning modelling

Objective: Learn a time step

- Mapping from current/previous atmospheric state(s) to next state
 - mapping specified by neural network
 - size of state variable: ≈ 100 million
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 - use of long datasets like 40 years of ERA5
 - mean square error (weighted) commonly applied loss function
 - stochastic gradient descent



Deep learning

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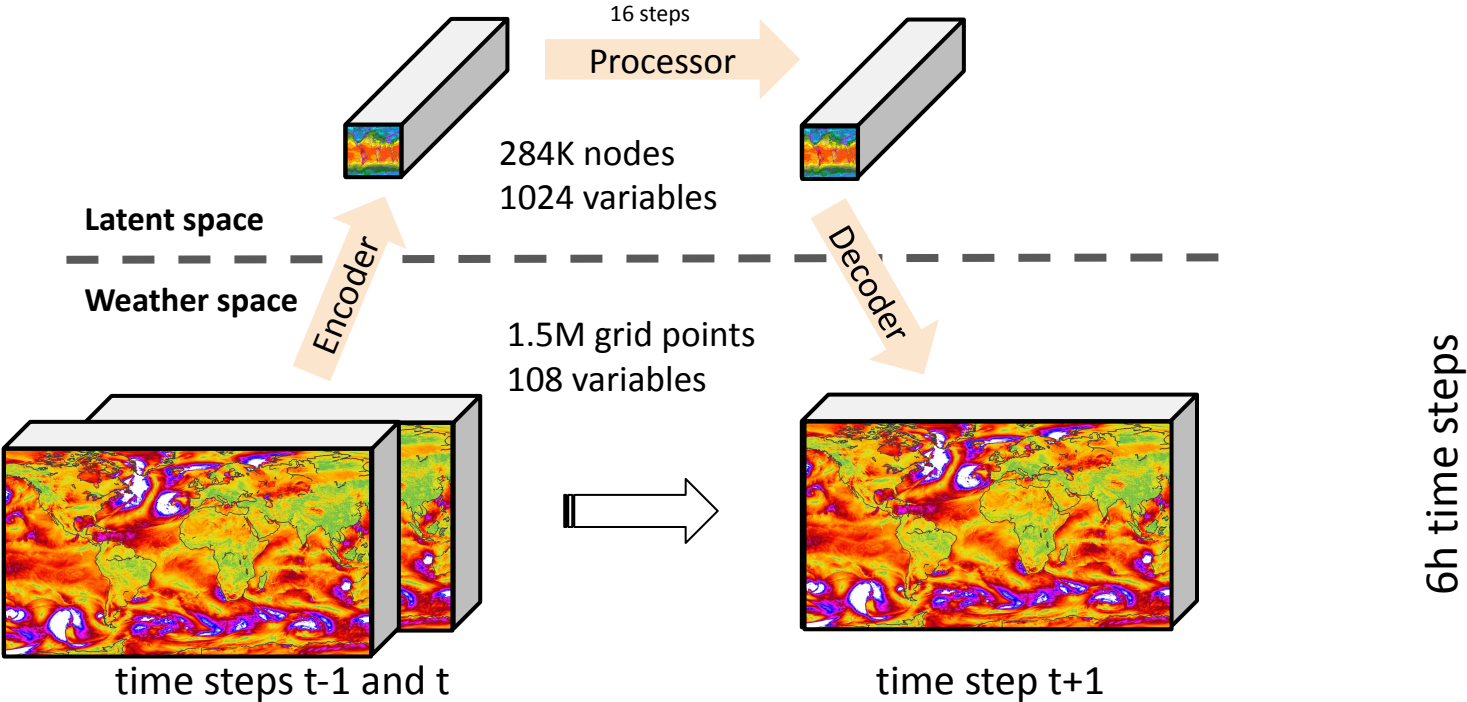
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- Learned time step applied to generate longer forecasts (auto-regression)

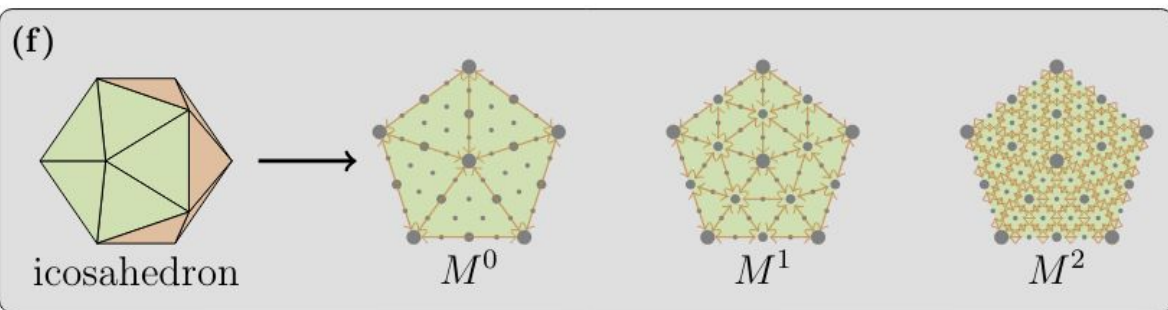
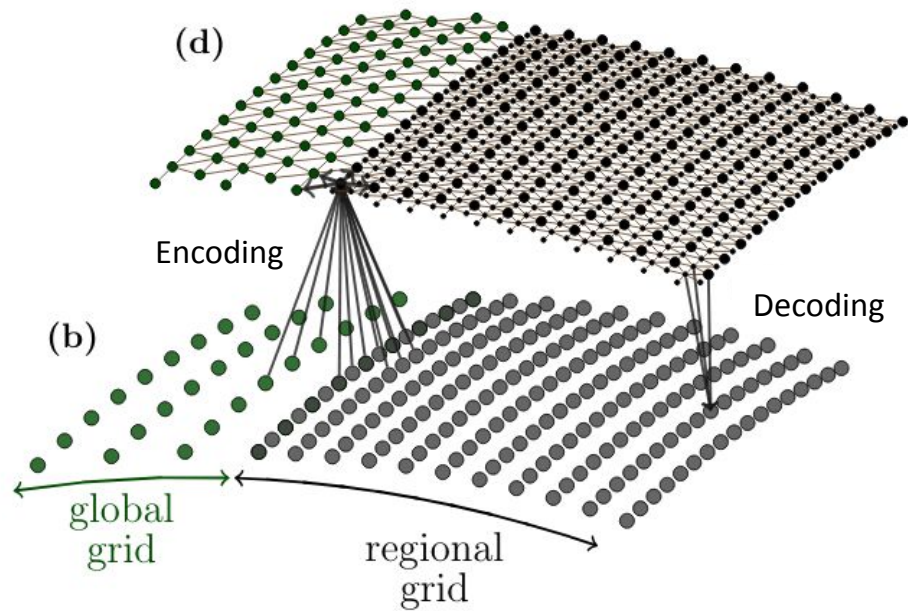
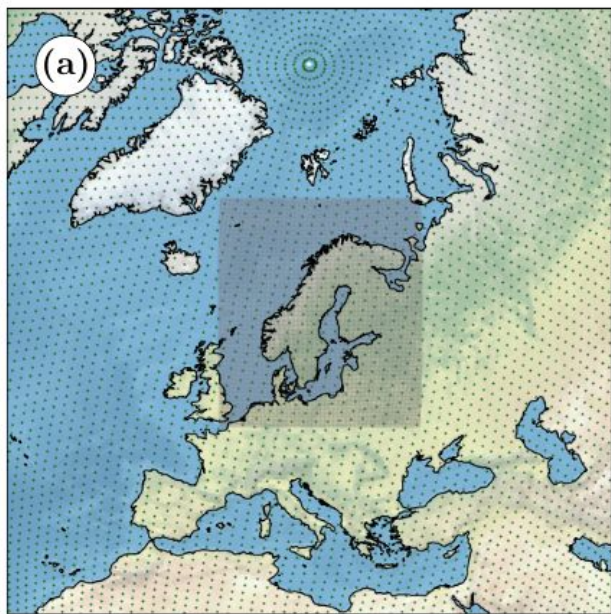


Deep learning

Bris model architecture

Auto-regressive encoder-processor-decoder





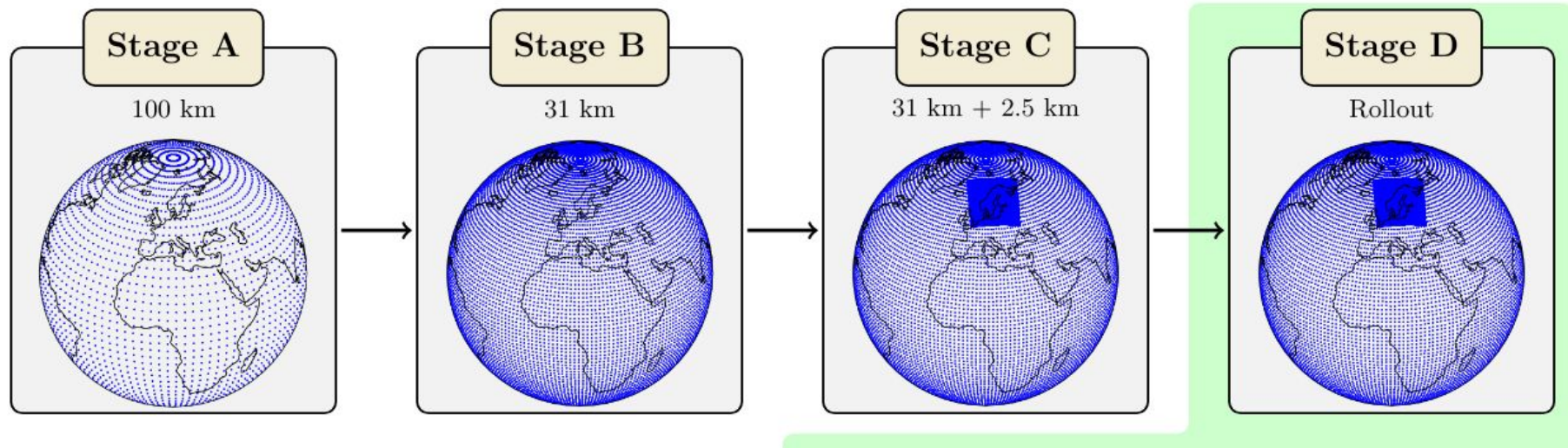
Training data: ERA5 (40 years) + MEPS analyses (3 years)

6-hour time resolution



- Input and output variables
 - T, U, V, W, Z, Q at 13 pressure levels
 - 13 single level fields (T0, T2, Td2, U10, V10, MSLP, surface pressure, cloud area fraction, ...)
- Additional diagnostic/output variables
 - precipitation, wind gust, visibility, fog
- Forcing input variables
 - solar insolation
 - elevation, land-sea mask
 - longitude, latitude
 - time of year and day

Training in four stages



Training and prediction

Training:

250 million trainable parameters

10 TB of training data

Global pre-training: approx 4000 GPU hours

High resolution fine-tuning: approx 2000 GPU hours

Generating forecasts:

NVIDIA H200 approx 2 min 10 day forecast

NVIDIA A100 approx 4 min 10 day forecast



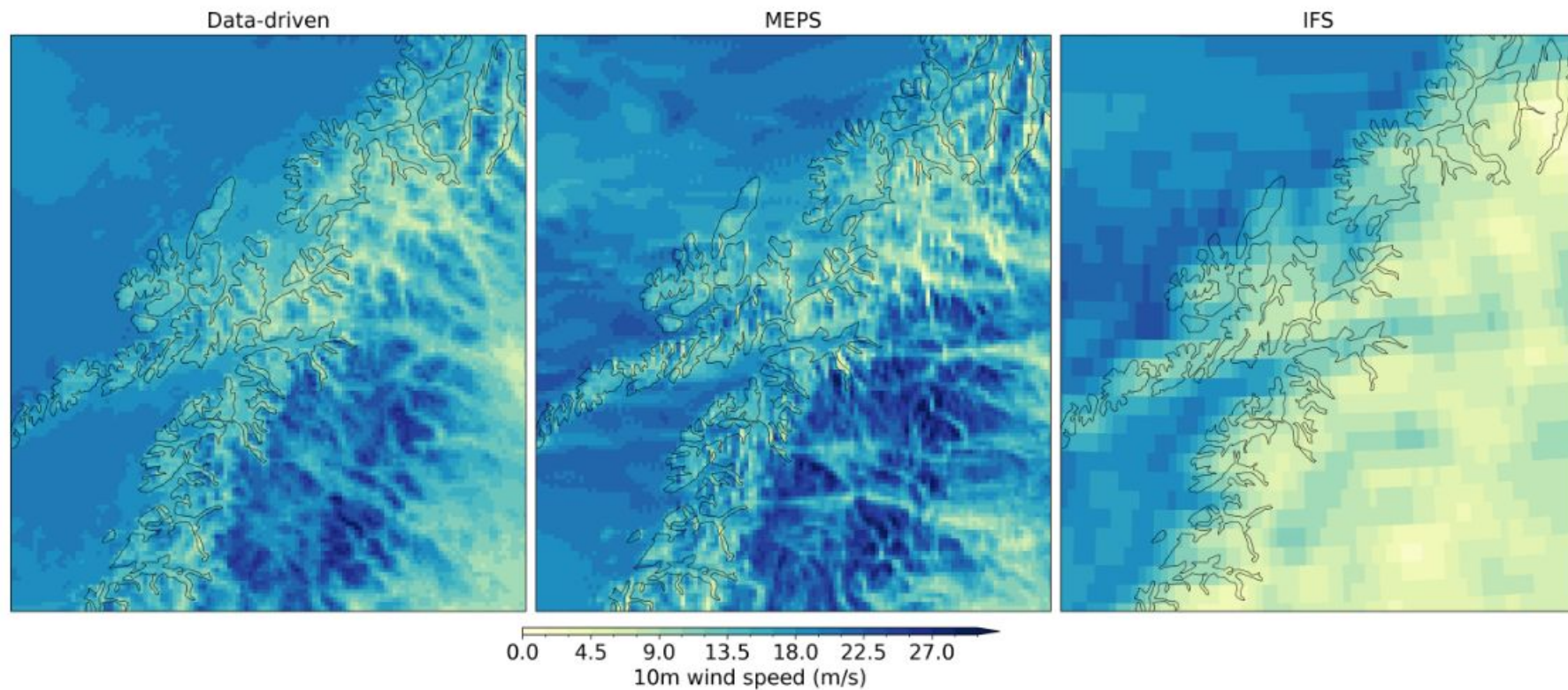
LUMI supercomputer

What can we expect based on statistical knowledge?

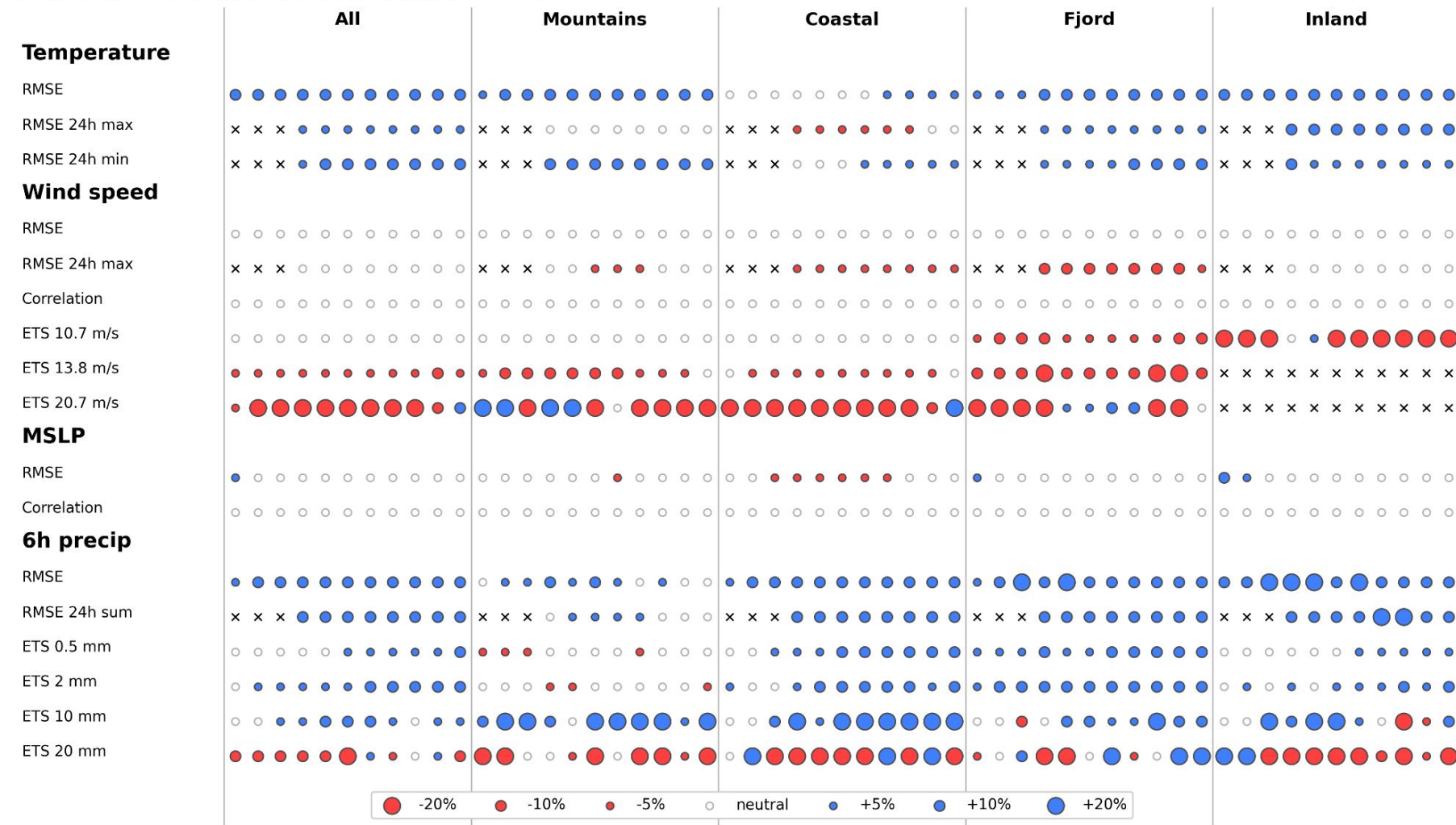
Optimising with respect to square error implies

- model predicts/estimates distribution means, not a realisations
 - less variation than the reference data (here reanalyses)
 - extremes will on average be under-estimated
 - fields are spatially smoother than the reference
- interpretation as distribution means only for the first 6h-time step
- for longer lead times variability is larger than distribution means
 - with increasing lead time
 - distribution mean → climatological mean value
 - model has about the same variability as for the first time step(?)

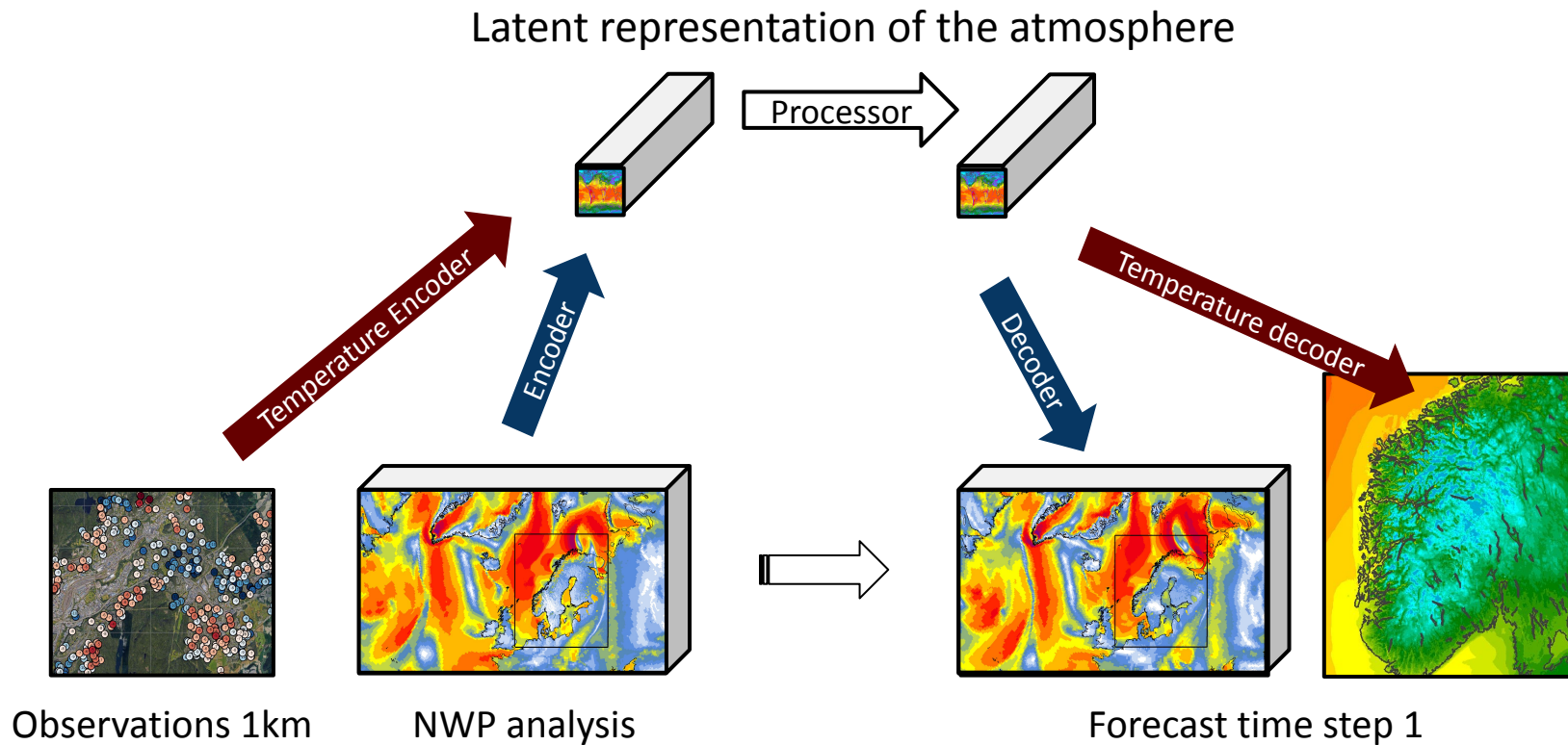
Wind speed example



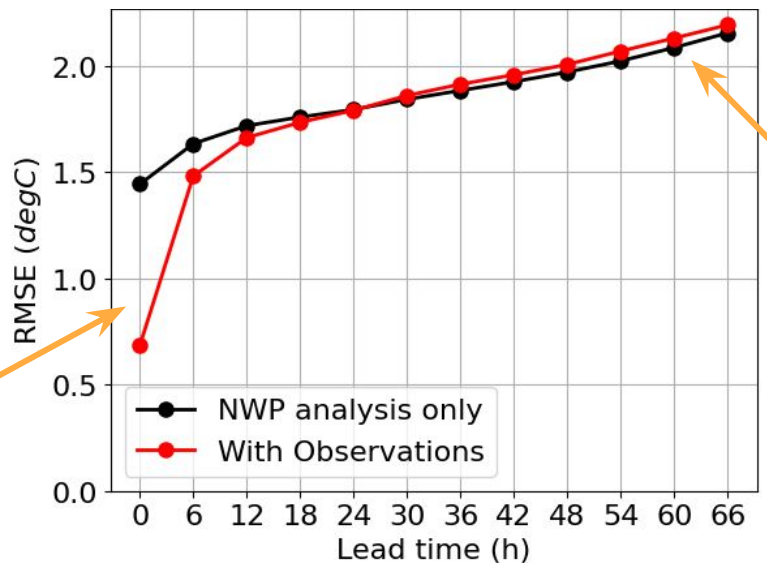
BRIS vs MEPS control score card



Integrating additional gridded fields



Improvement
from fusing
observations

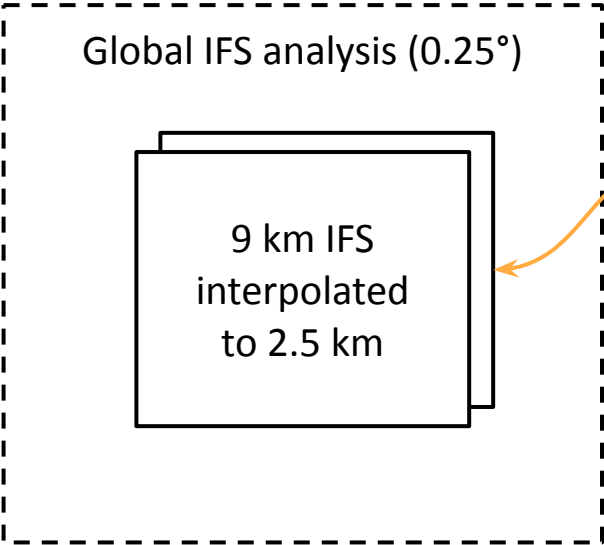
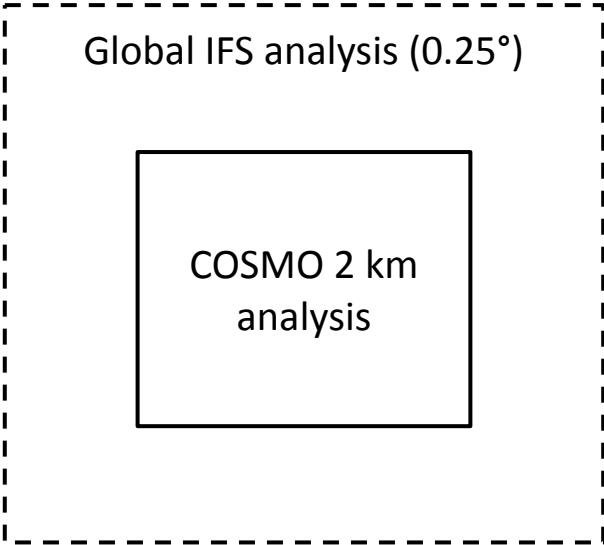


Still some work
to do...

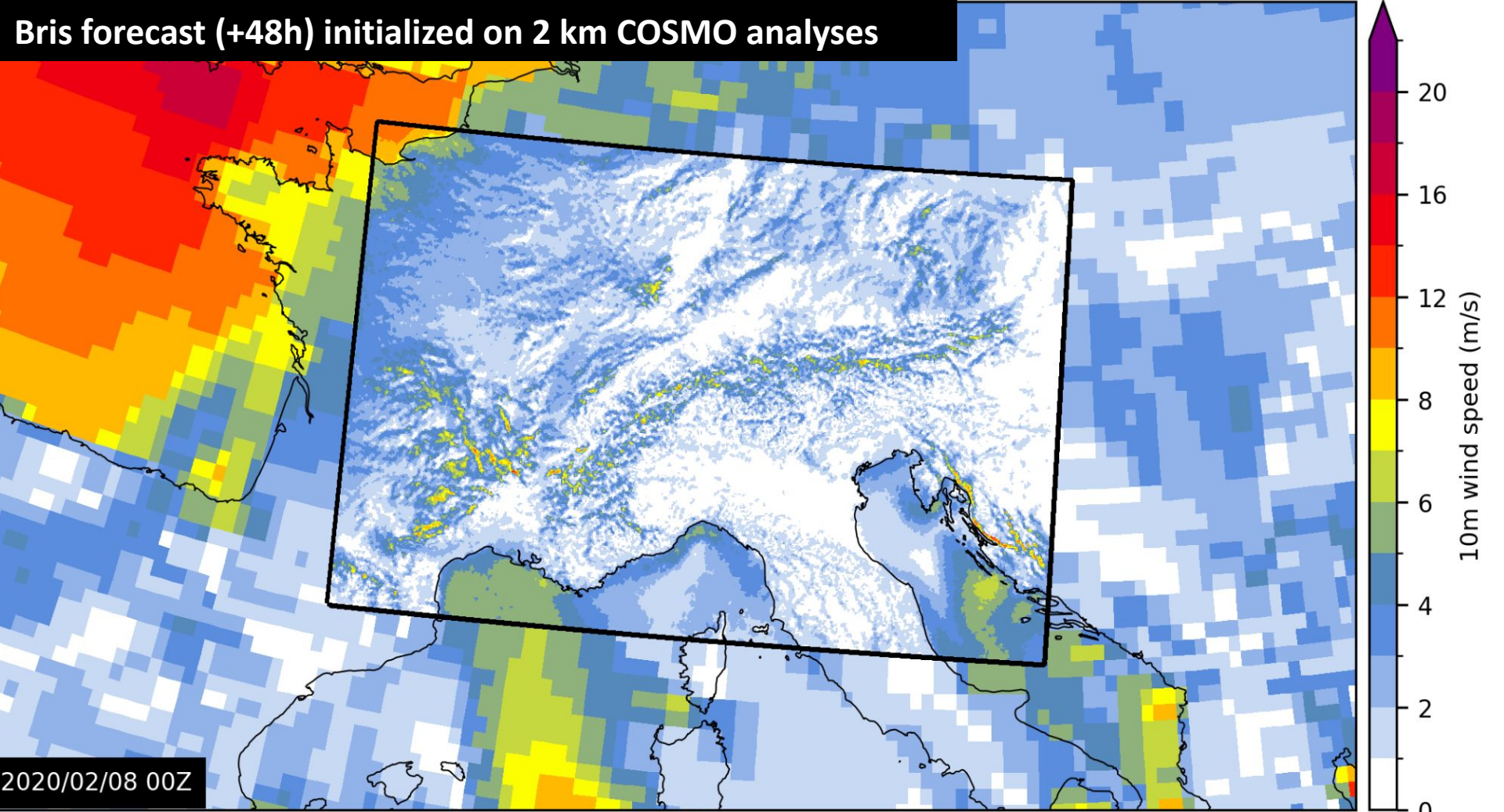
Does Bris generalise to other regions?

Experiment 1: Bris initialized from MeteoSwiss analyses

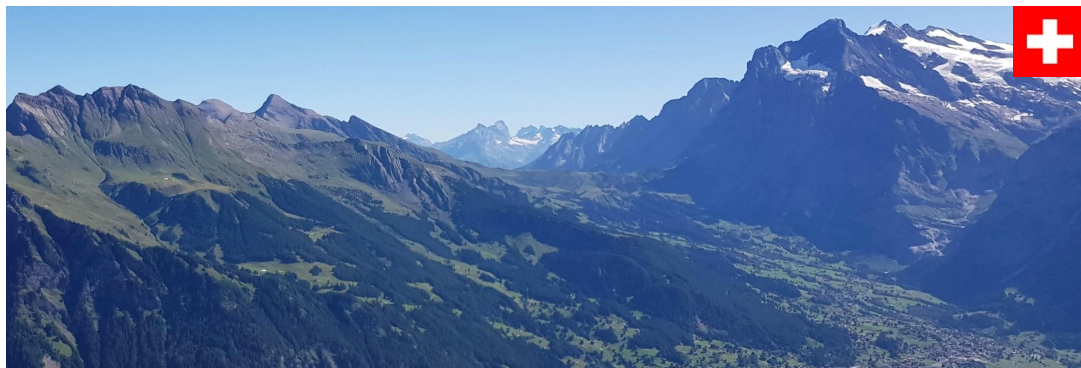
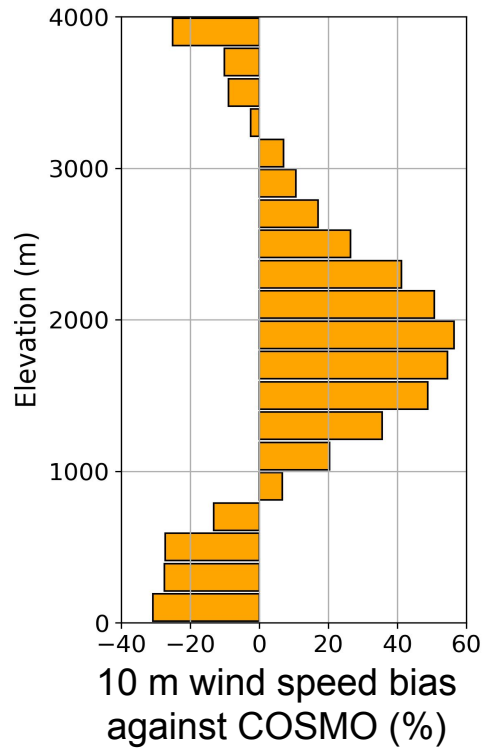
Experiment 2: Bris initialized entirely from IFS analyses



Bris forecast (+48h) initialized on 2 km COSMO analyses

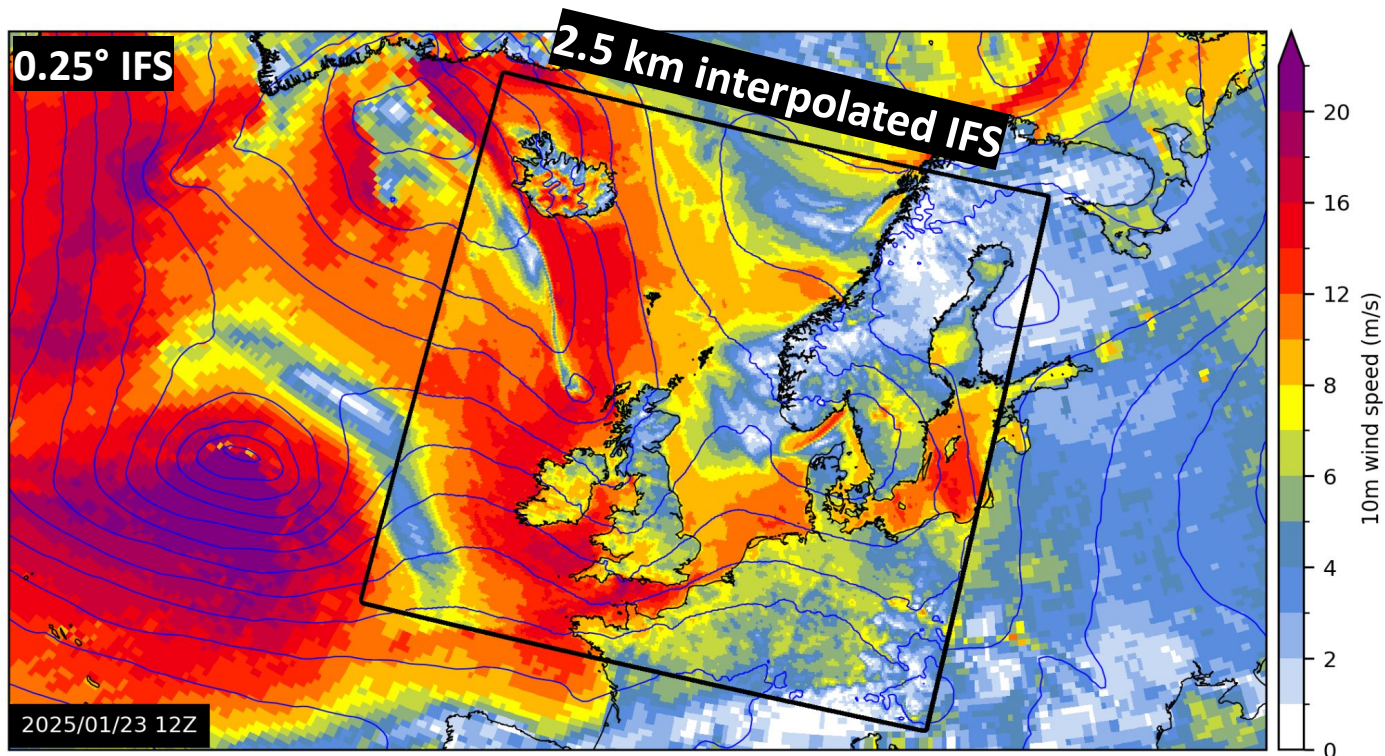


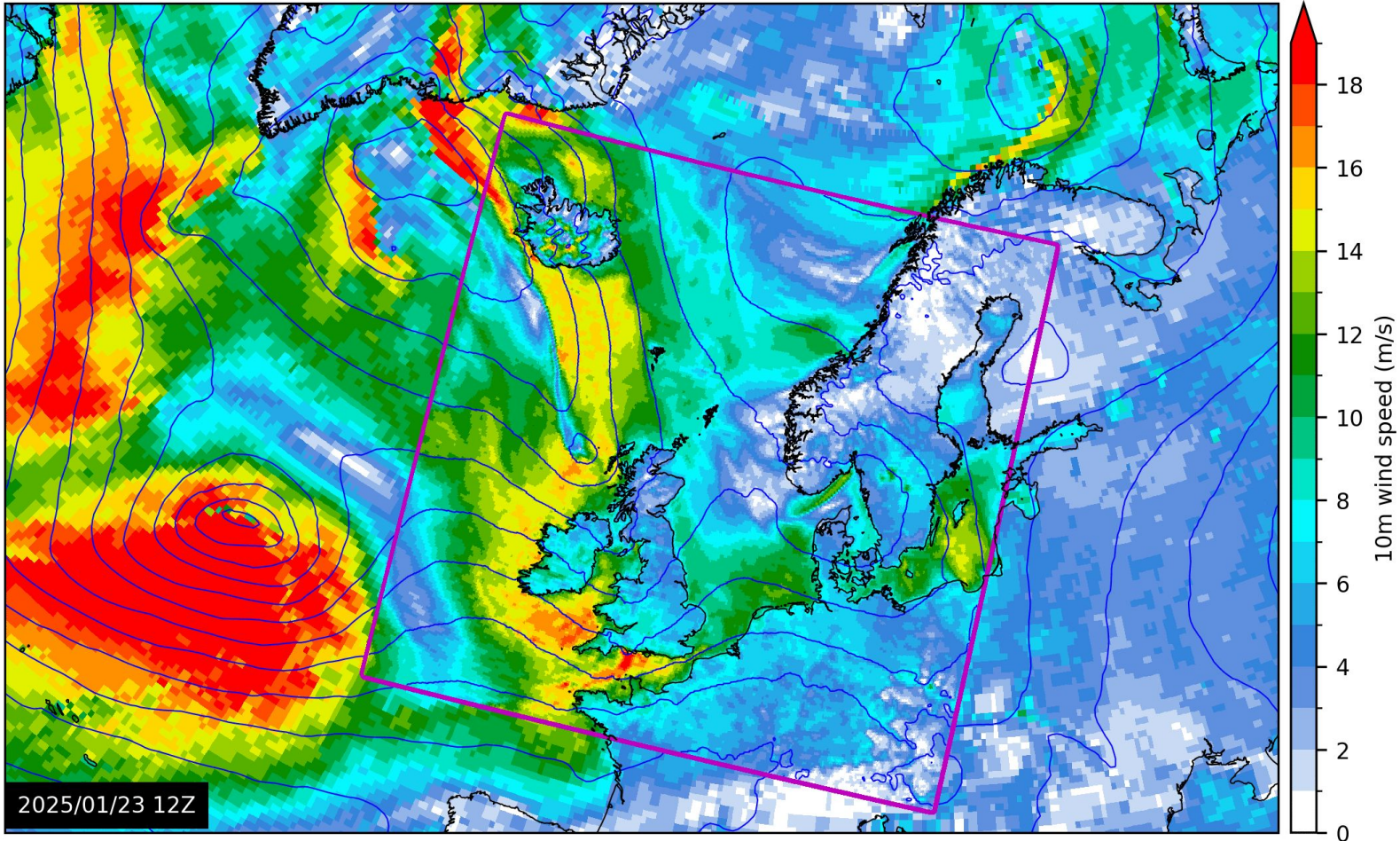
*Thanks to MeteoSwiss for providing data



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EOWYN - initialised with downscaled IFS







Training data



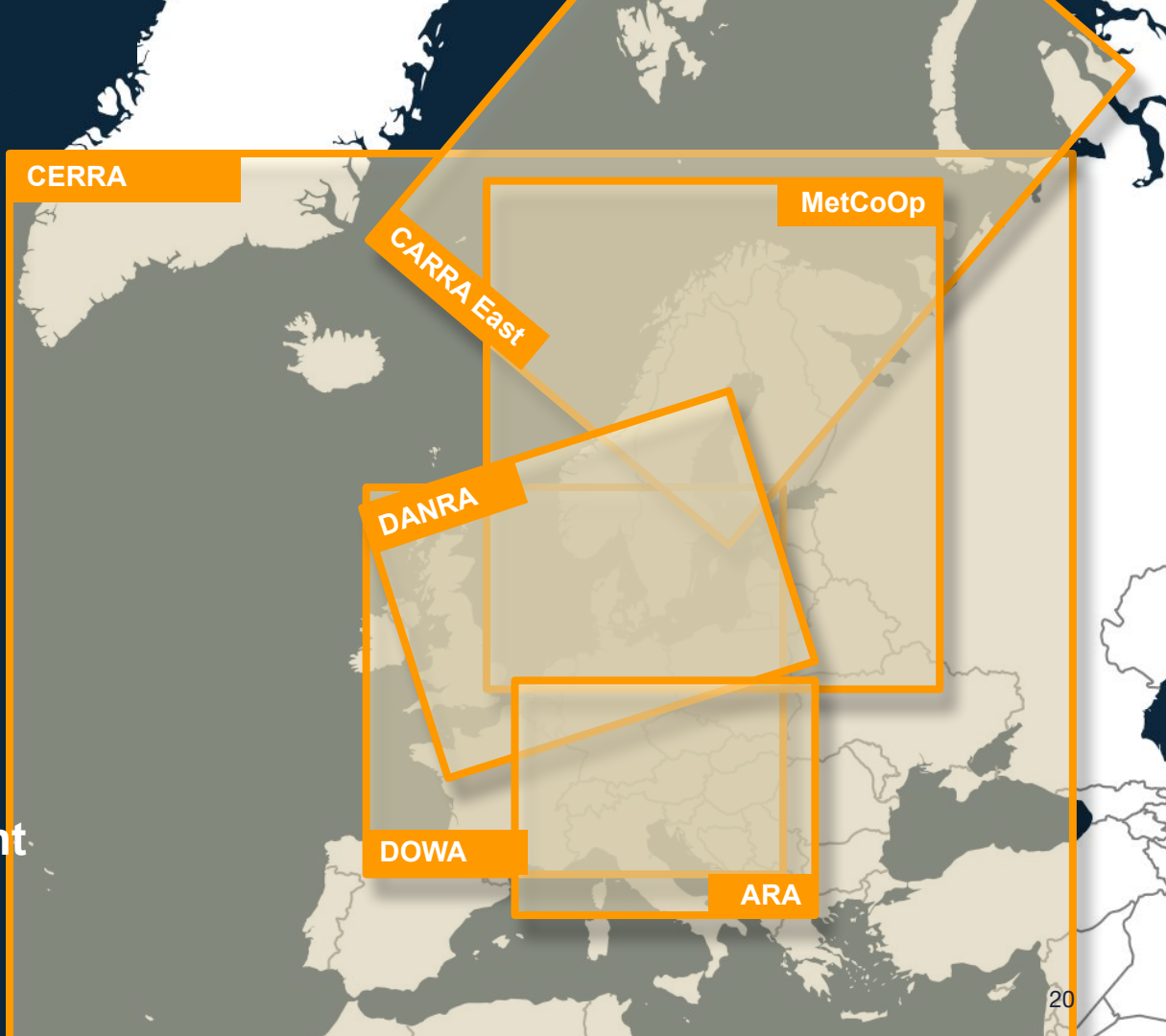
**European
reanalyses**
5.5 km



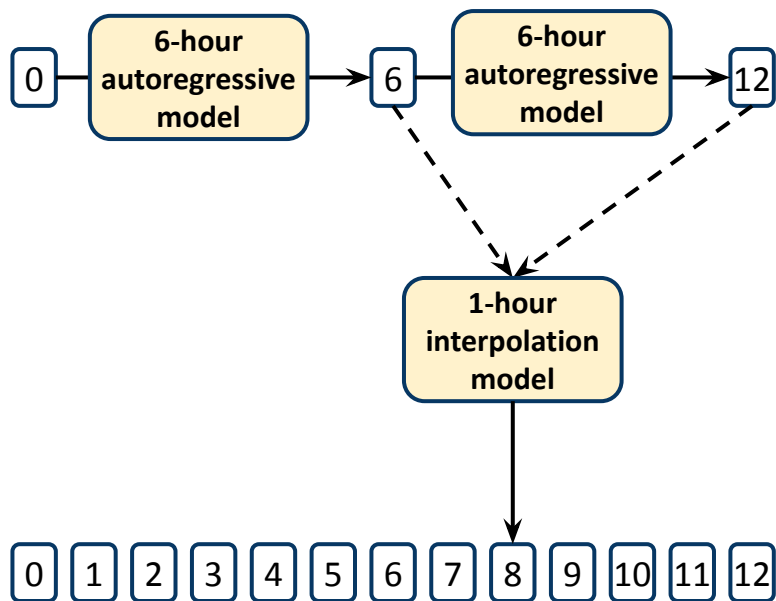
**Regional
reanalyses**
2.5 km



**DE330 extreme event
simulations**
200-750m

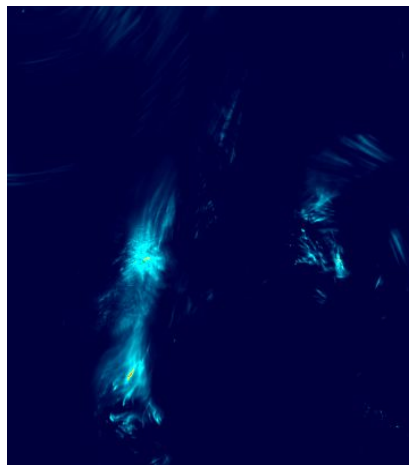


Hourly resolution by time interpolation model

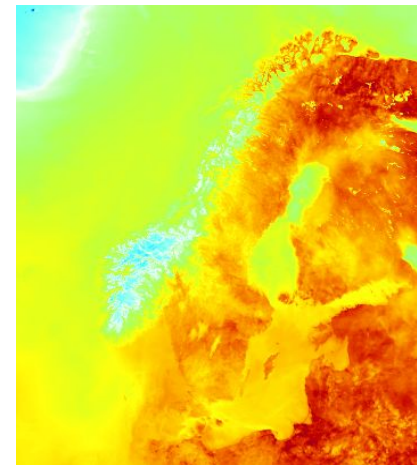


Trained on forecast data,
uses full state of model
for 0 and 6 hours

6h precip



2m temperature



Available as a feature in anemoi-core

Magnus Sikora

Ongoing work and next steps

- Set up a Bris model for **tests** in downstream applications (yr.no) before summer
 - include all variables needed
 - hourly resolution
 - temperature on 1-km grid
 - output in netcdf format (as for MEPS, IFS)
- Ensemble generation
 - optimisation based on CRPS
 - scenarios less smooth than in deterministic Bris as expected
 - probabilistic verification scores already good
 - challenges with spatial coherence
- More verification
 - assessment of model features
- More high-resolution training data
 - CARRA2
- Multi-domain training
 - joint work in DE330
- Data-assimilation
 - joint work in Machine Learning Pilot Project